

AT-algebras associated to zero-dimensional dynamical systems

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Goal

AT-algebras
associated to
zero-dimensional
dynamical
systems

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Expanding our knowledge of non-simple C^* -algebra classification.

Motivation

Setting

The First
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The Second
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The Third
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Expanding our knowledge of non-simple C^* -algebra classification.

Determine a condition on a zero-dimensional dynamical system such that the crossed product is AT and has real rank zero, thus allowing us to apply the previous (not necessarily simple) AT -algebra classification results (Elliott; Dadarlat-Gong).

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Determine a condition on a zero-dimensional dynamical system such that the crossed product is AT and has real rank zero, thus allowing us to apply the previous (not necessarily simple) AT -algebra classification results (Elliott; Dadarlat-Gong).

This was already done in the minimal case (Putnam '90) and the essentially minimal case with no periodic points (Herman-Putnam-Skau '92).

Zero-Dimensional Systems

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A dynamical system (X, h) is a pair where X is a topological space and $h : X \rightarrow X$ is a homeomorphism.

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A dynamical system (X, h) is a pair where X is a topological space and $h : X \rightarrow X$ is a homeomorphism.

We will consider only *zero-dimensional dynamical systems*, by which we mean dynamical systems where X is compact, totally disconnected, and metrizable.

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Examples of such X :

- Finite spaces with the discrete topology.
- Compactifications of the integers.
- The Cantor set.

Minimality

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A dynamical system (X, h) is *minimal* if all orbits are dense; i.e. the only nonempty closed invariant subset of X is X .

Examples:

- $X = \mathbb{Z}/n\mathbb{Z}$ and h is the shift.
- X is the Cantor set and h is the 2-odometer.

Essential Minimality

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A dynamical system (X, h) is *essentially minimal* if there is a unique smallest nonempty closed invariant subset of X . This smallest set is called the *minimal set*.

Examples:

- Any minimal system. The minimal set is X .
- X is the one-point compactification of the integers and h is the shift. The minimal set is the fixed point at infinity.

Crossed Products

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Given (X, h) , we associate to it a *crossed product* C^* -algebra, which we will denote by $C^*(\mathbb{Z}, X, h)$, that “encodes the dynamical information” of the system. The most convenient way to think of it is the C^* -algebra generated by $C(X)$ and a unitary u such that

$$(u^* f u)(x) = f(h^{-1}(x)).$$

$A\mathbb{T}$ -Algebras and Real Rank Zero

$A\mathbb{T}$ -algebras
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For our purposes, we will think of $A\mathbb{T}$ -algebras as C^* -algebras that can be approximated arbitrarily well by circle algebras, which are direct sums of matrices and matrices over $C(S^1)$.

AT -Algebras and Real Rank Zero

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For our purposes, we will think of AT -algebras as C^* -algebras that can be approximated arbitrarily well by circle algebras, which are direct sums of matrices and matrices over $C(S^1)$.

Without giving a formal definition, we can consider *real rank zero* to be a condition on a C^* -algebra that tells us that there are "many projections".

The First Theorem

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Theorem (H. '21)

Let (X, h) be a zero-dimensional system that for any partition \mathcal{P} of X , (X, h) admits a system of finite first return time maps subordinate to \mathcal{P} . Then $C^*(\mathbb{Z}, X, h)$ is an AT-algebra.

Finite First Return Time Maps

Given (X, h) and a subset $Y \subset X$, we may define the "first return time map" $\lambda_Y : X \rightarrow \mathbb{Z}_{>0} \cup \{\infty\}$ by

$$\lambda_Y(x) = \inf\{n \in \mathbb{Z}_{>0} \mid h^n(x) \in Y\}$$

if the infimum exists, and $\lambda_Y(x) = \infty$ otherwise. This map tells us "how long it takes a point in Y to come back to Y ".

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Finite First Return Time Maps

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Some things to note:

- If X is minimal and Y is compact and open, then λ_Y is a finite subset of $\mathbb{Z}_{>0}$.
- If X is essentially minimal and Y is compact and open and intersects the minimal set of X , then λ_Y is a finite subset of $\mathbb{Z}_{>0}$.

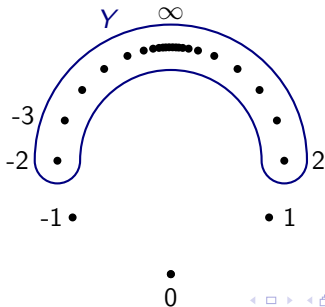
An Example

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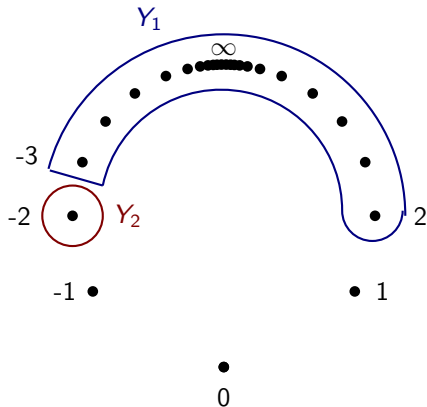
if the infimum exists, and $\lambda_Y(x) = \infty$ otherwise. This map tells us "how long it takes a point in Y to come back to Y ".

Consider the example of the one-point compactification of the integers with the shift homeomorphism.



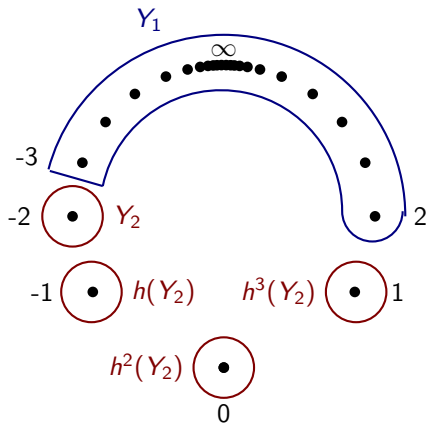
An Example

We split Y into pieces of constant first return time; the first return time of Y_1 is 1 and the first return time of Y_2 is 4.



An Example

We then use iterates to build a partition of X .



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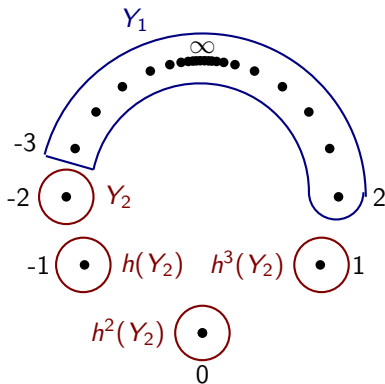
The Third
Theorem

An Example

Using this partition, one can construct a matrix algebra that contains (as the diagonal matrices) an approximation of $C(X)$. The matrix units have the form

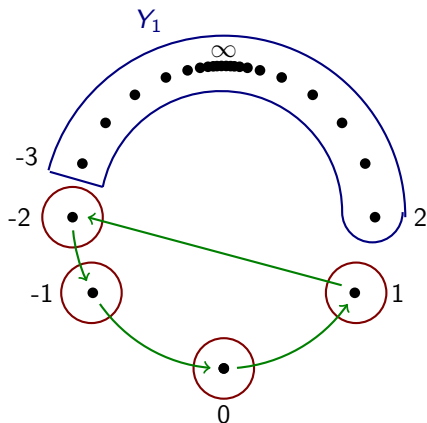
$$e_{i,j}^{(k)} = u^{i-j} \chi_{h^j(Y_k)}$$

and in our case is isomorphic to $\mathbb{C} \oplus M_4$.



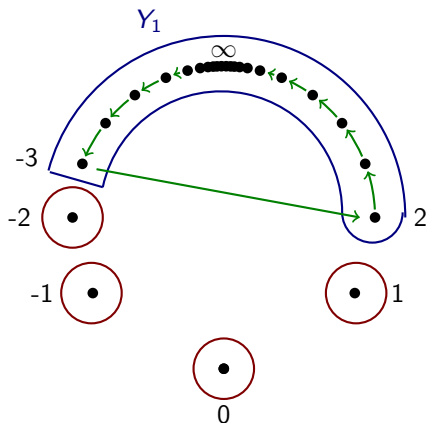
An Example

This matrix algebra does not approximate u very well. The best thing it has is the unitary $1 \oplus \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$ that does the following:



An Example

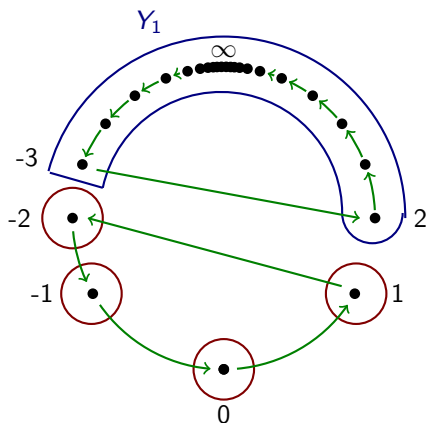
We then find a unitary in the crossed product that commutes with our matrix algebra that does the following:



An Example

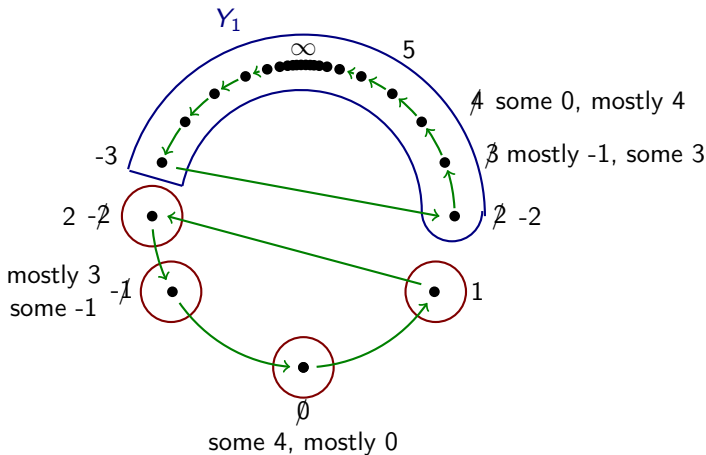
We then get a subalgebra $A \cong C(S^1) \oplus M_4$ that has a unitary

$$z \oplus \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} \text{ that does the following:}$$



An Example

This still isn't quite right, so we use a unitary v to move some stuff. When done carefully, v^*Av will be a circle algebra that contains an approximation of u .



The Theorem Revisited

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If one allows for finitely many such Y , this process still works and gives us an approximating circle algebra. Hence the previously referenced theorem:

Theorem (H. '21)

Let (X, h) be a zero-dimensional system that for any partition \mathcal{P} of X admits a system of finite first return time maps subordinate to \mathcal{P} . Then $C^*(\mathbb{Z}, X, h)$ is an AT-algebra.

The Second Theorem

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**The Second
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What do dynamical systems for which the first result applies look like?

The Second Theorem

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What do dynamical systems for which the first result applies look like?

Theorem (H. '21)

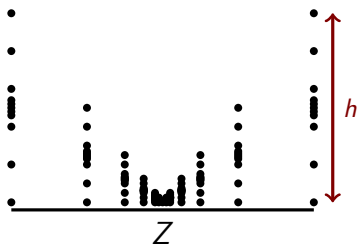
Let (X, h) be a zero-dimensional system. Then (X, h) is fiberwise essentially minimal if and only if for any partition \mathcal{P} of X admits a system of finite first return time maps subordinate to \mathcal{P} .

An Example Generator

Theorem (H. '21)

Let (X, h) be a zero-dimensional system. Then (X, h) is fiberwise essentially minimal if and only if for any partition \mathcal{P} of X admits a system of finite first return time maps subordinate to \mathcal{P} .

Without going into too much detail, *fiberwise essentially minimal* zero-dimensional look like this:



The Third Theorem

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Theorem (H. '21)

Let (X, h) be a fiberwise essentially minimal zero-dimensional system with no periodic points. Then $C^*(\mathbb{Z}, X, h)$ has real rank zero.

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Theorem (H. '21)

Let (X, h) be a fiberwise essentially minimal zero-dimensional system with no periodic points. Then $C^*(\mathbb{Z}, X, h)$ has real rank zero.

Altogether, we have shown that if (X, h) is fiberwise essentially minimal with no periodic points, then $C^*(\mathbb{Z}, X, h)$ is $A\mathbb{T}$ and has real rank zero, making it classifiable. Note that the first theorem actually didn't require the no periodic points assumption to yield $A\mathbb{T}$.